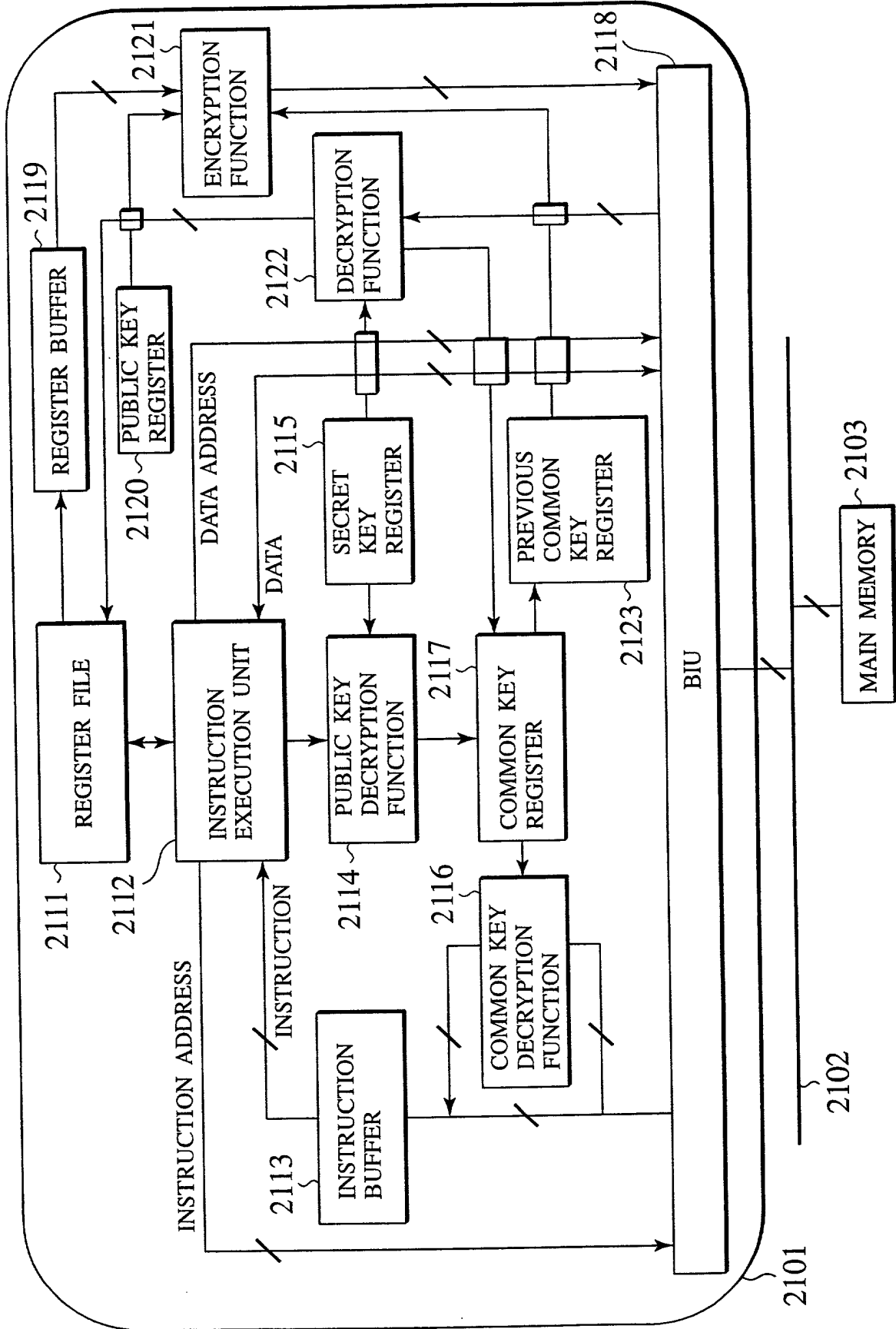


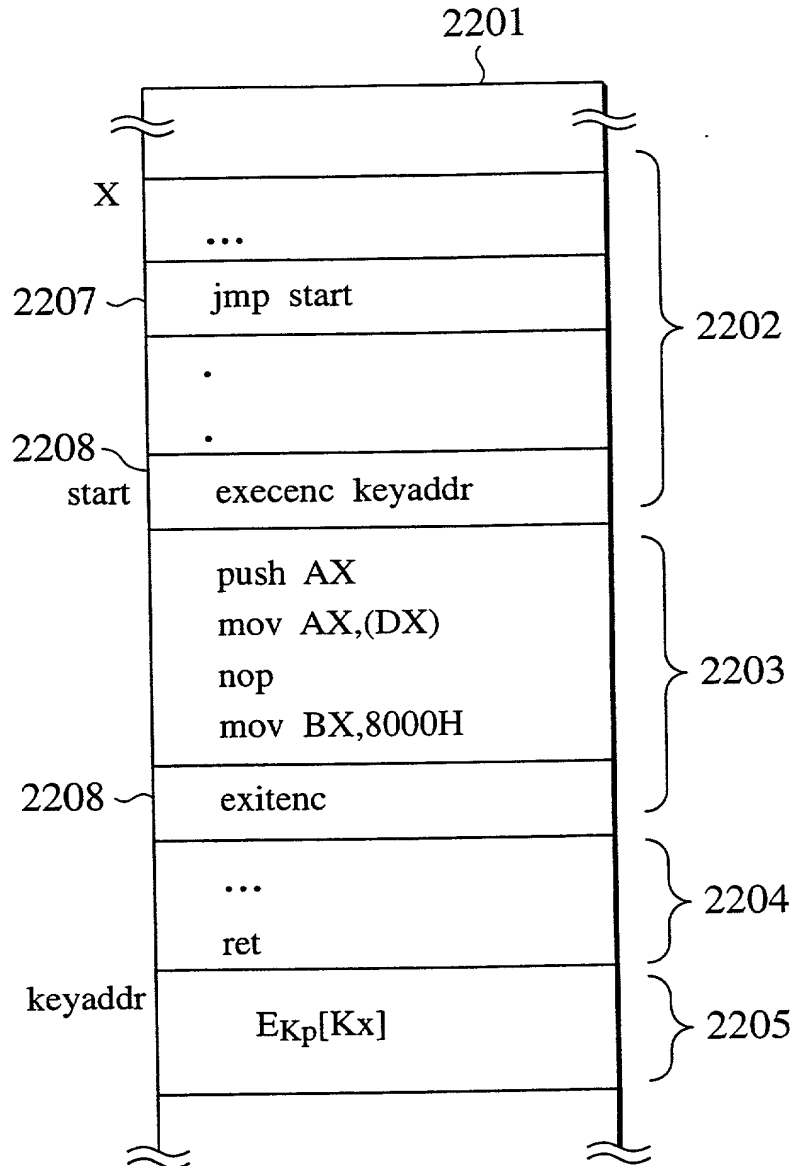
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FIG.1



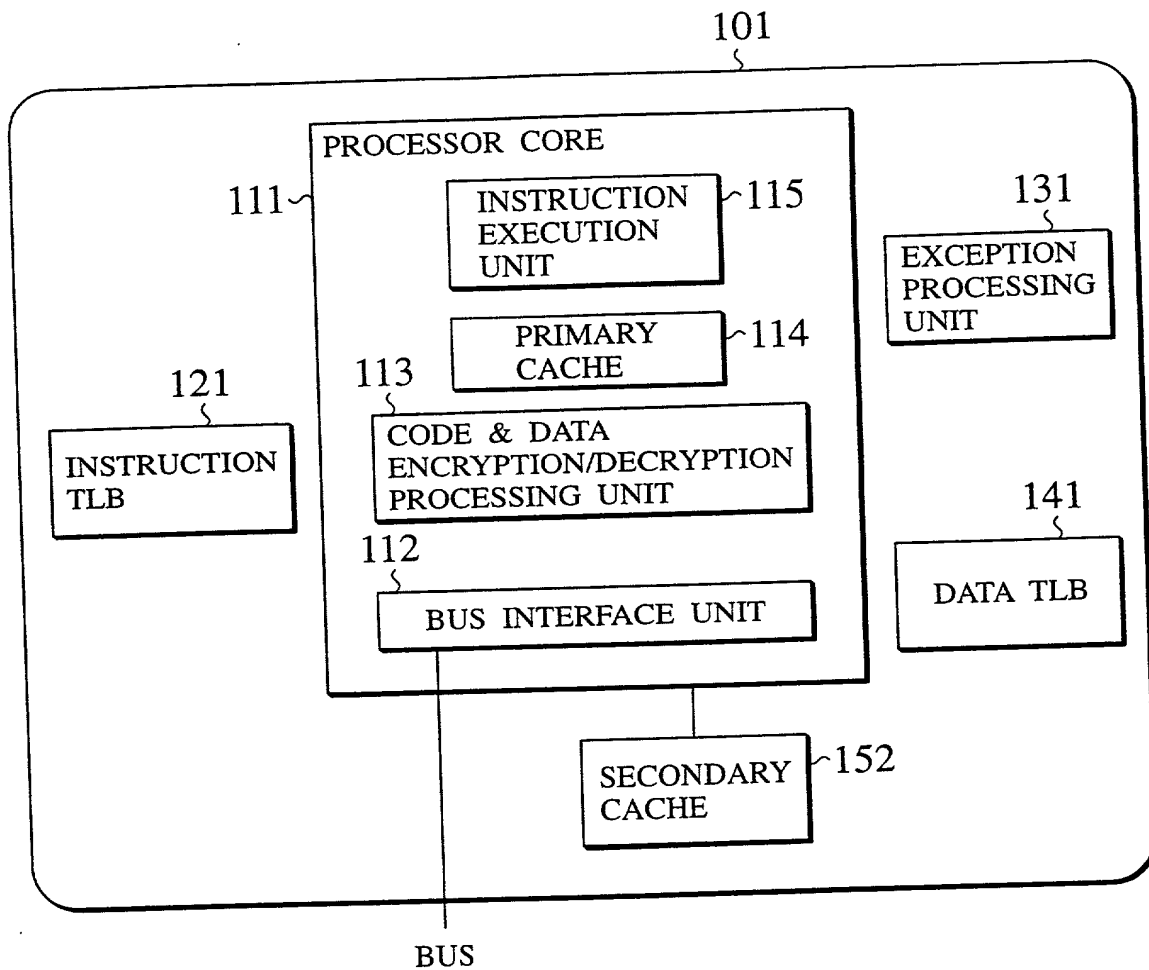
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FIG.2



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FIG.3



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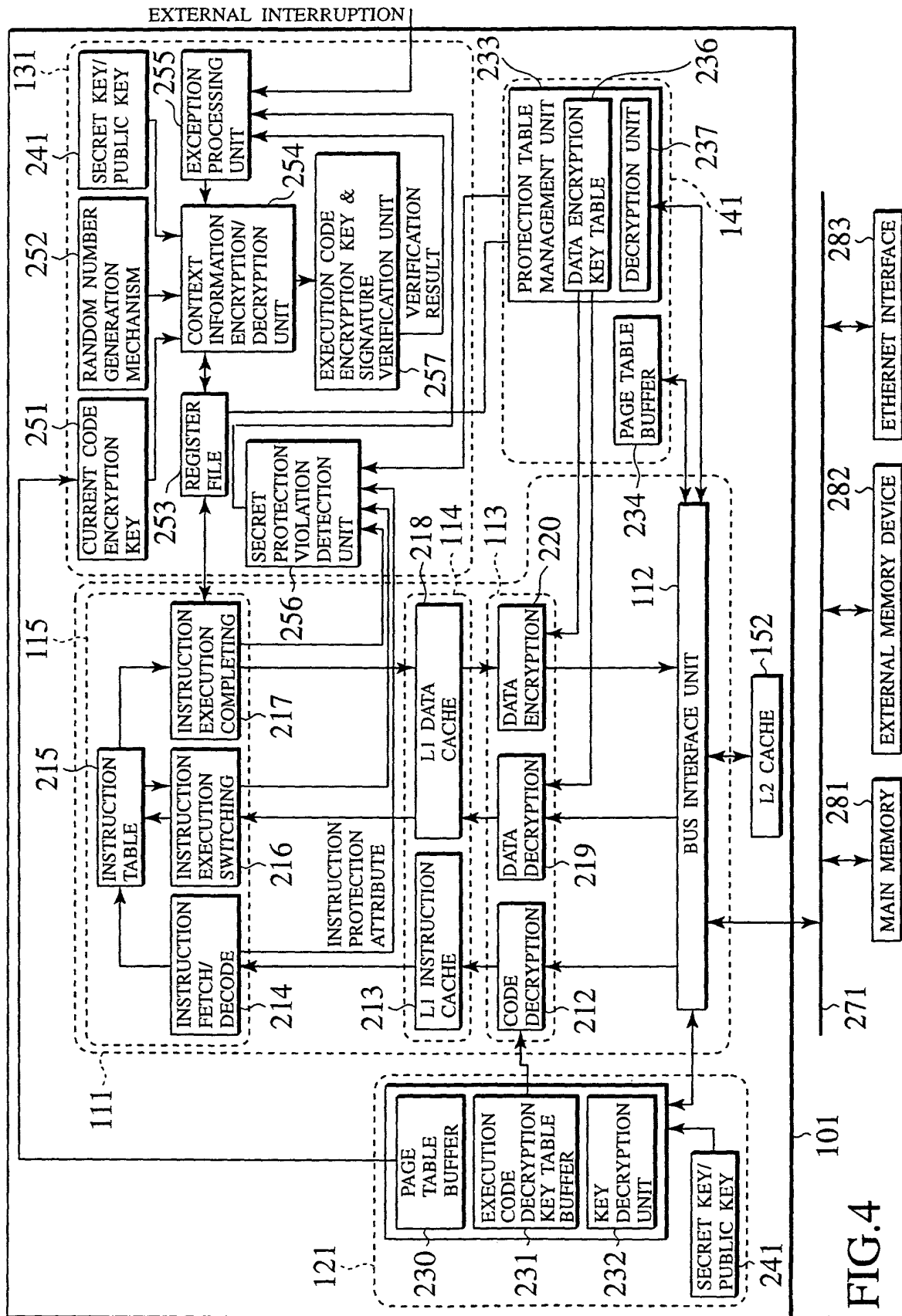
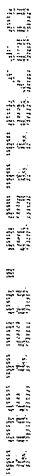
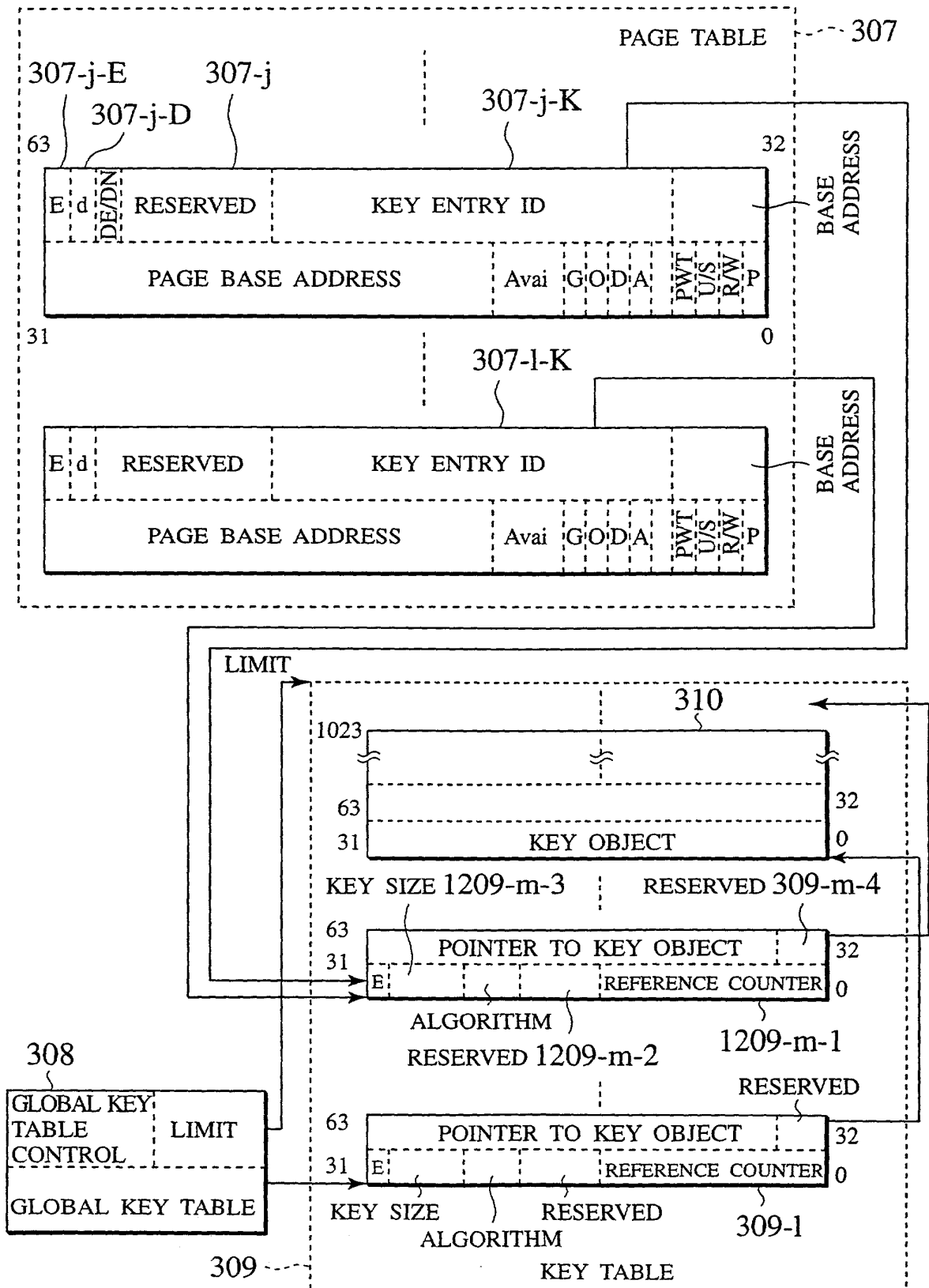


FIG. 4

1. The first group of authors (e.g., [1, 2]) considers the problem of the control of the motion of a mechanical system with a variable structure. The control is realized by means of a feedback control system. The control is realized by means of a feedback control system. The control is realized by means of a feedback control system.



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FIG.6



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FIG.7A

	0	1	2	3
0	A0	A1	A2	A3
1	B0	B1	B2	B3
2	C0	C1	C2	C3
3	D0	D1	D2	D3
4	E0	E1	E2	E3
5	F0	F1	F2	F3
6	G0	G1	G2	G3
7	H0	H1	H2	H3

BEFORE INTERLEAVING

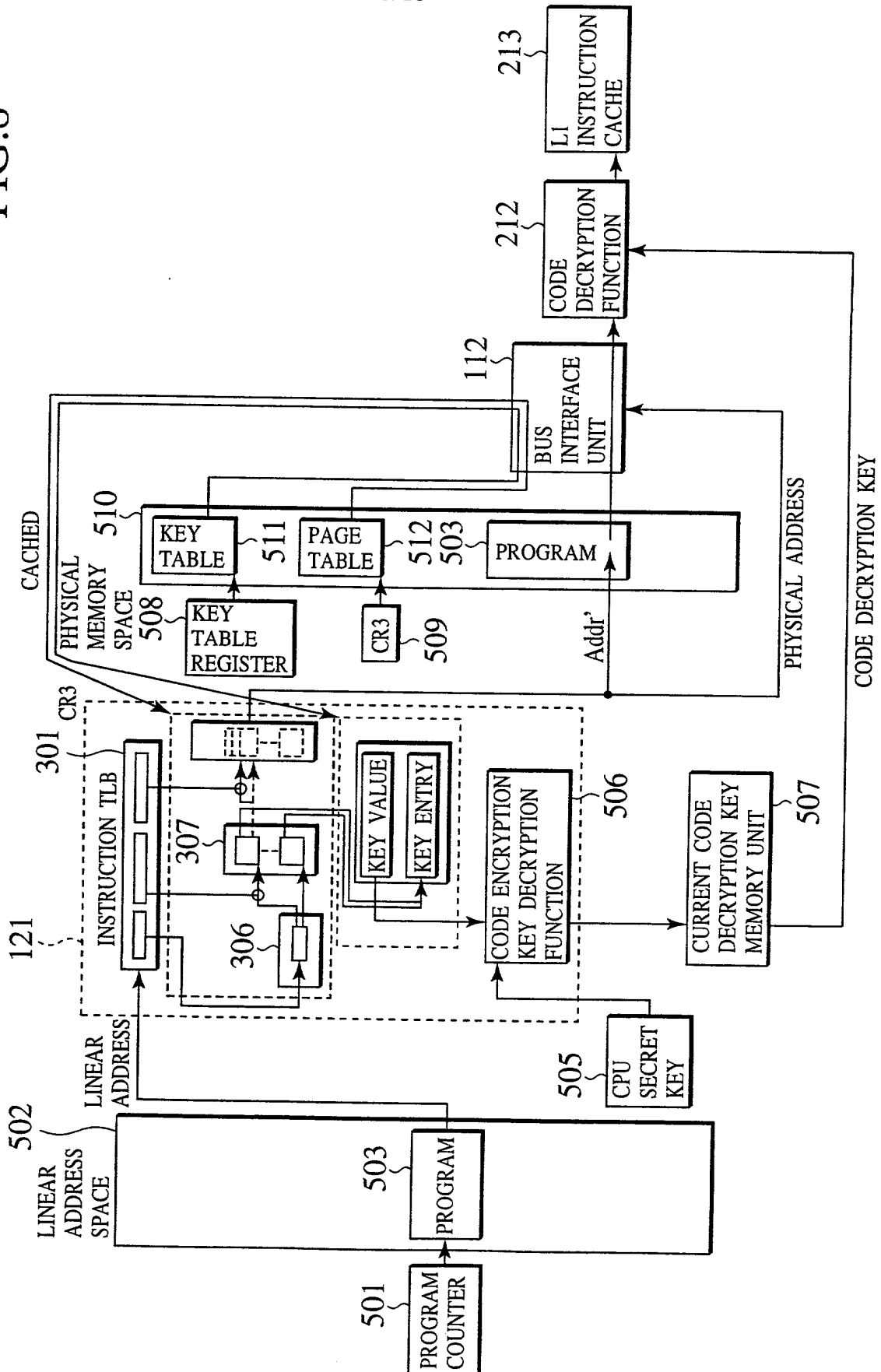
FIG.7B

0	A0	B0	C0	D0
1	E0	F0	G0	H0
2	A1	B1	C1	D1
3	E1	F1	G1	H1
4	A2	B2	C2	D2
5	E2	F2	G2	H2
6	A3	B3	C3	D3
7	E3	F3	G3	H3

AFTER INTERLEAVING

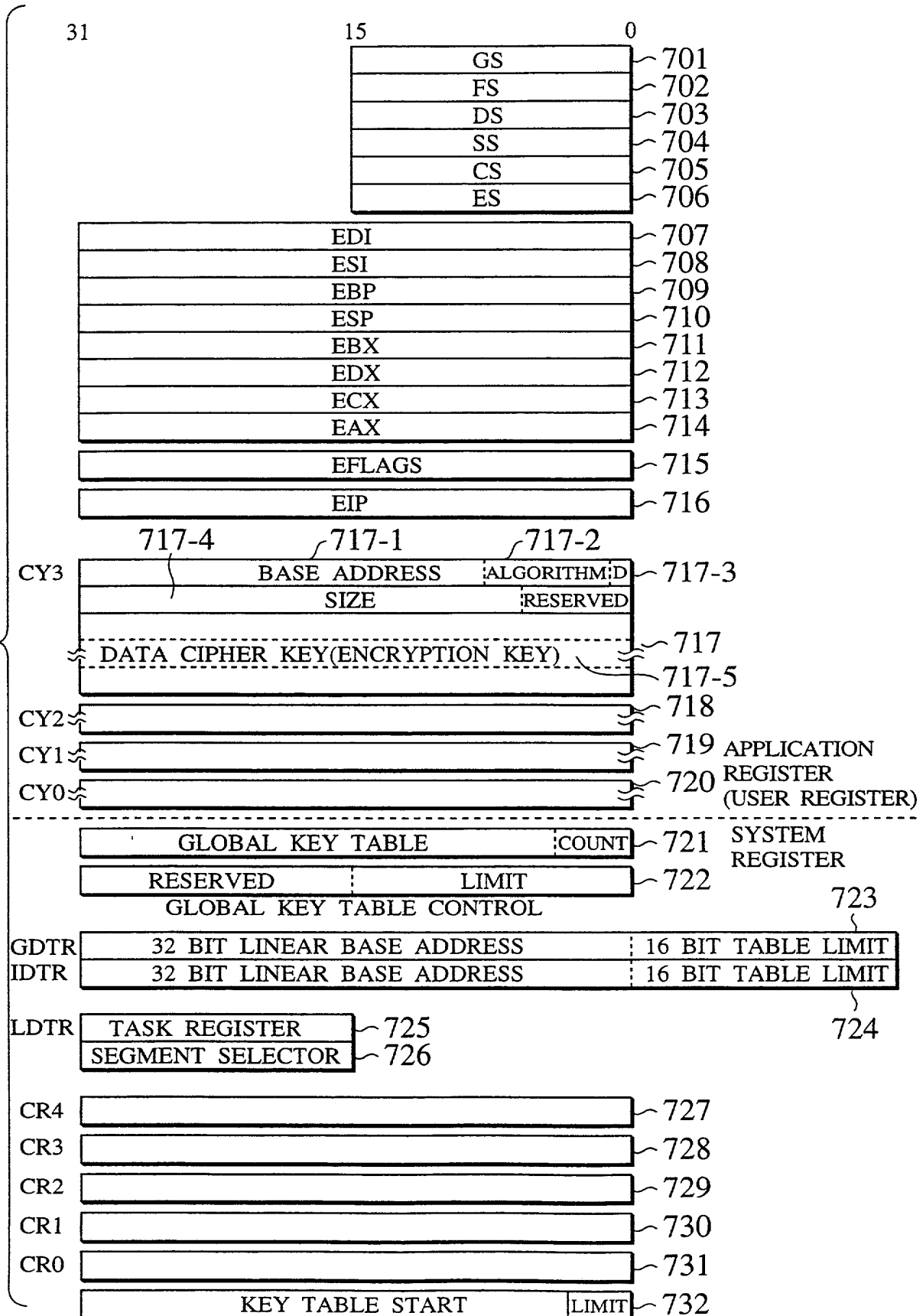
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FIG. 8



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FIG.9



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FIG.10

S[message] by Ks		834
E[Kr] by Kp		833
E[Kr] by Kcode		832
PADDING		831
BASE ADDRESS	RESERVED	E
SIZE		
DATA ENCRYPTION KEY FOR CY3		830
DATA ENCRYPTION CONTROL REGISTER (CY2)		829
DATA ENCRYPTION CONTROL REGISTER (CY1)		828
DATA ENCRYPTION CONTROL REGISTER (CY0)		827
TSS SIZE		826
I/O MAP BASE ADDRESS		825
	LDT SEGMENT SELECTOR	824
	GS	823
	FS	822
	DS	821
	SS	820
	CS	819
	ES	818
EDI		817
ESI		816
EBP		815
ESP		814
EBX		813
EDX		812
ECX		811
EAX		810
EFLAGS		809
EIP		808
CR3(PDBR)		807
	SS2	806
ESP2		805
	SS1	804
ESP1		803
	SS0	802
ESP0		801
LINK TO PREVIOUS TASK		

825-1

825-2

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FIG.11

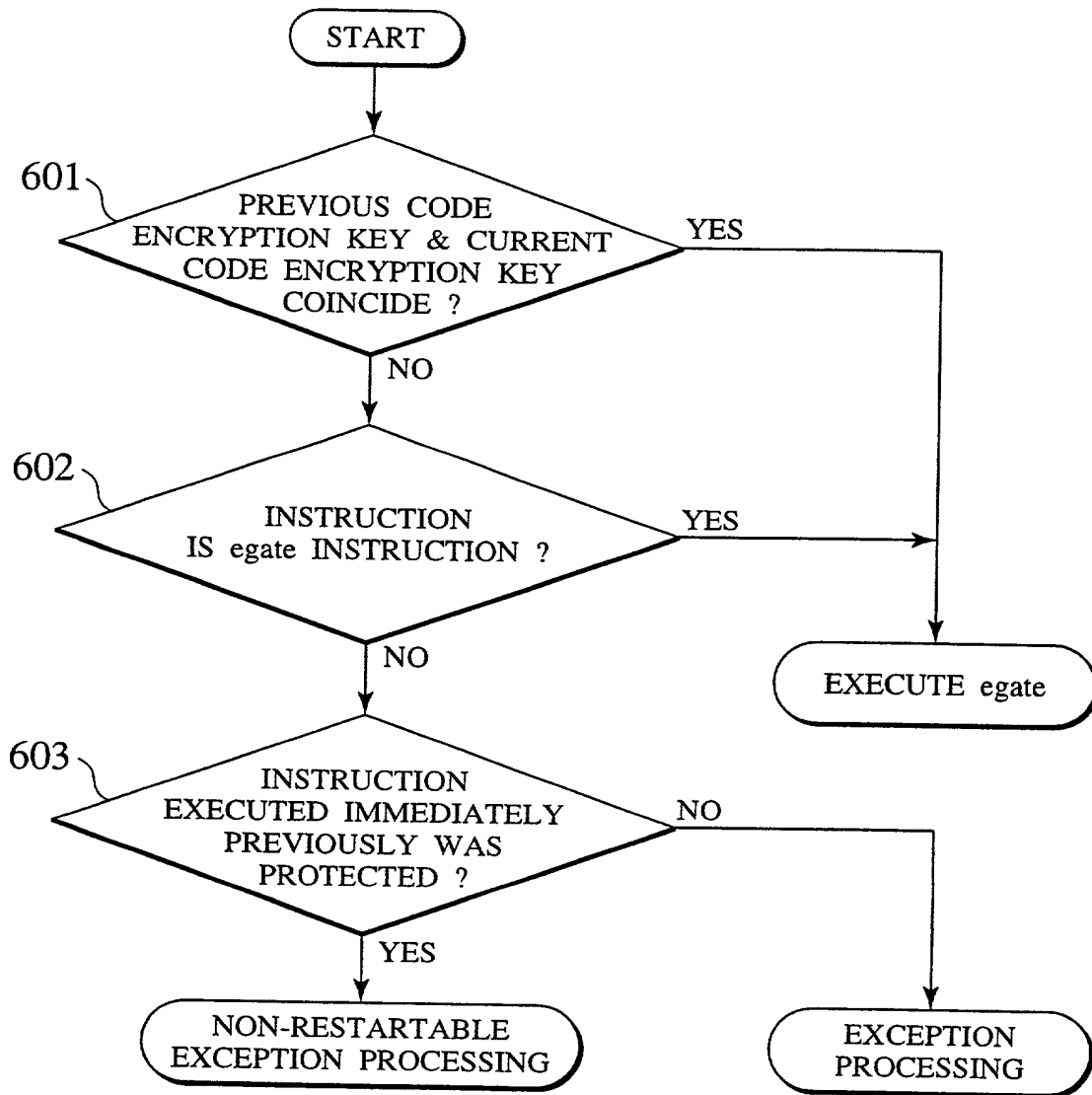
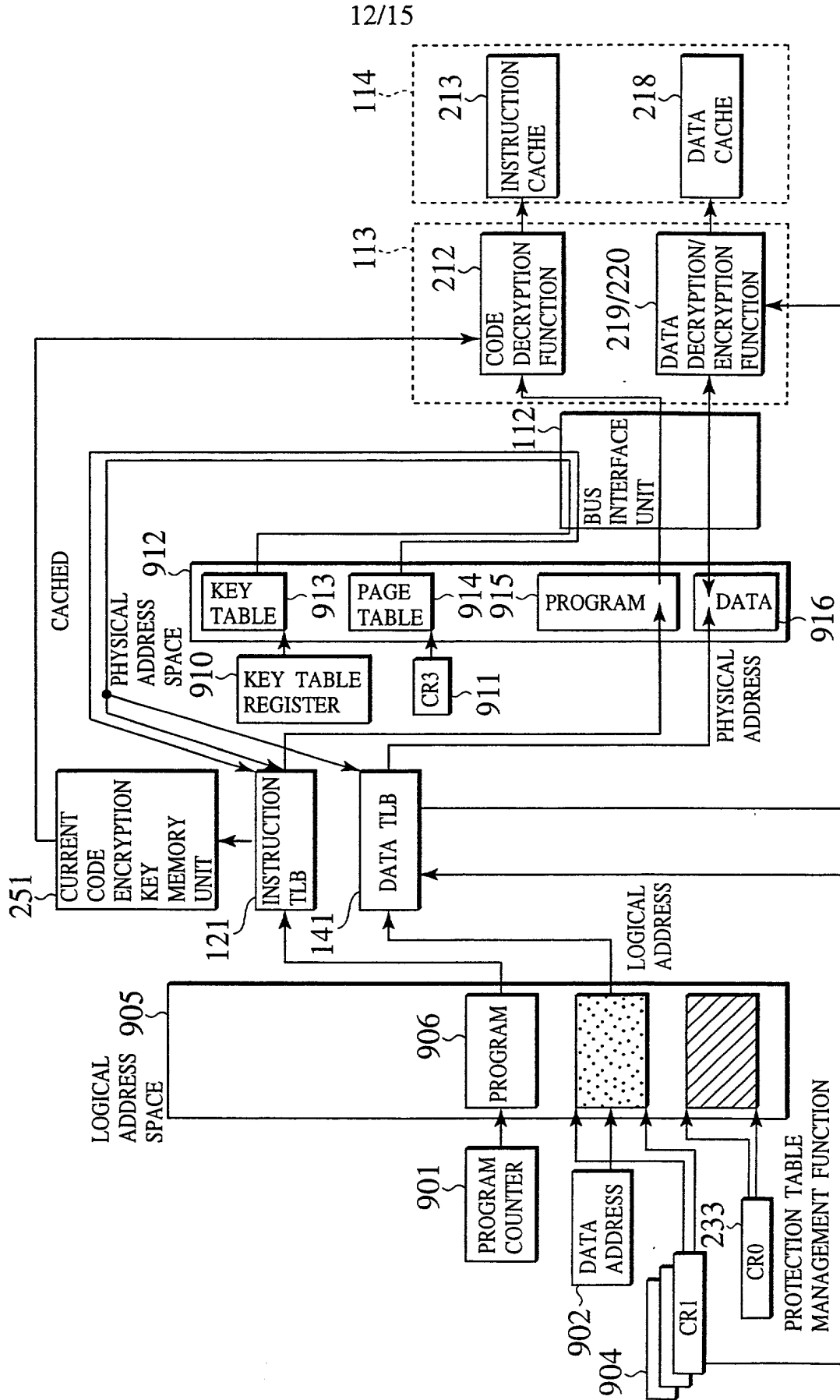
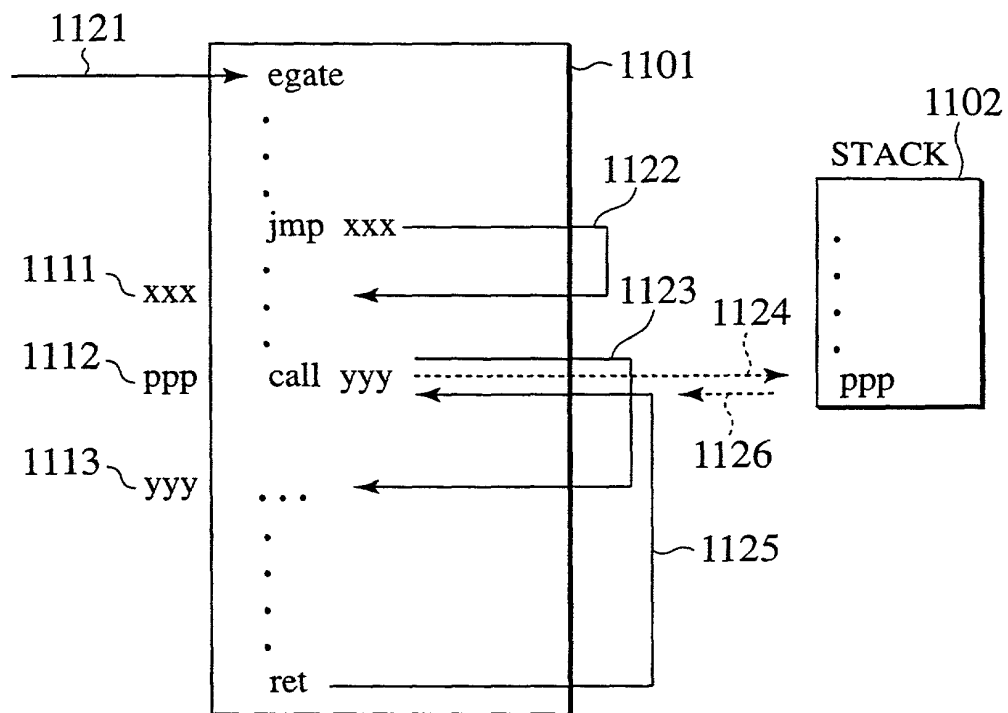


FIG.12



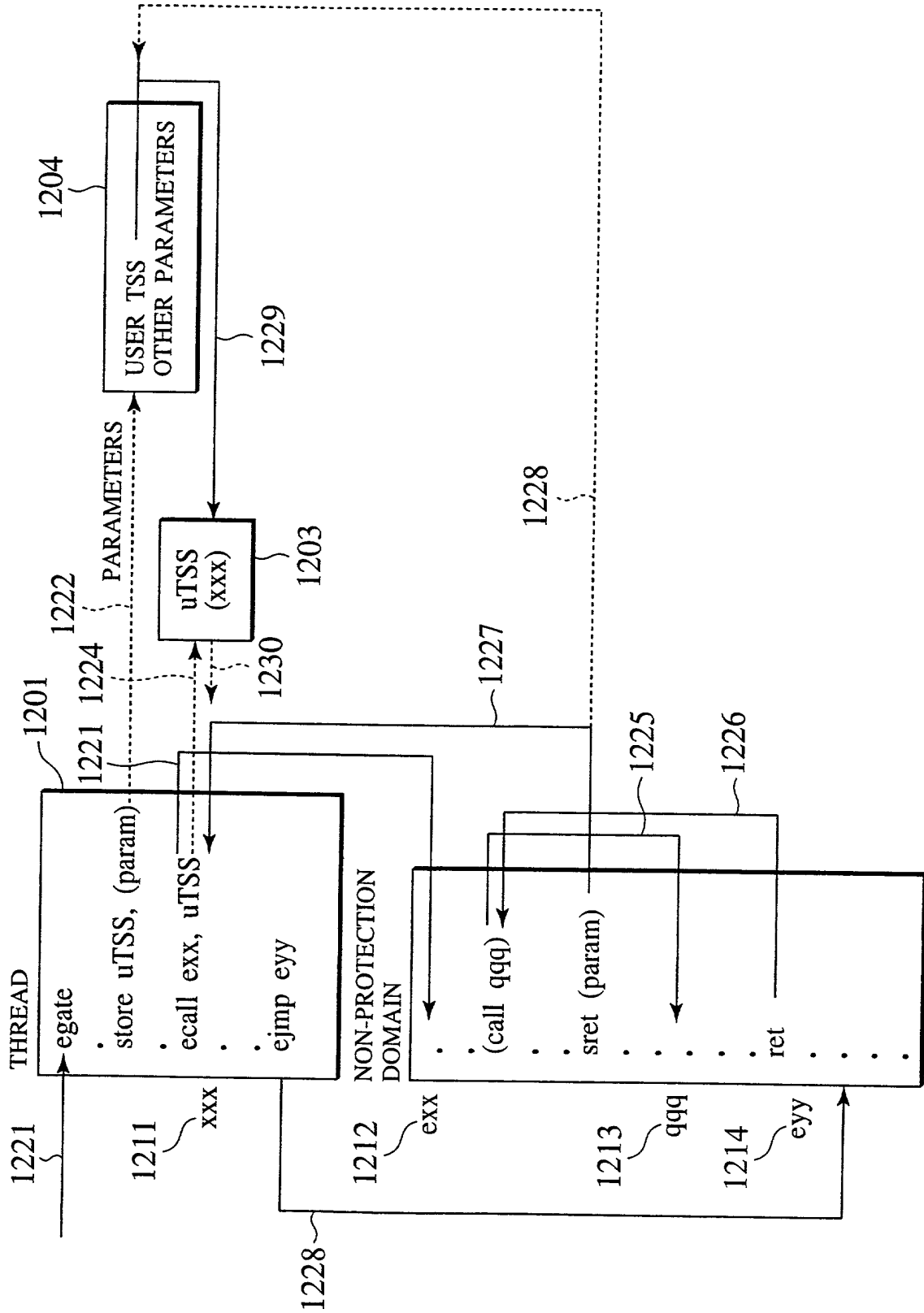
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FIG. 13



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FIG.14



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FIG.15 PRIOR ART

31	15	0	
I/O MAP BASE ADDRESS		T	100
	LDR SEGMENT SELECTOR		96
	GS		92
	FS		88
	DS		84
	SS		80
	CS		76
	ES		72
	EDI		68
	ESI		64
	EBP		60
	ESP		56
	EBX		52
	EDX		48
	ECX		44
	EAX		40
	EFLAGS		36
	EIP		32
	CR3(PDBR)		28
	SS2		24
	ESP2		20
	SS1		16
	ESP1		12
	SS0		8
	ESP0		4
	LINK TO PREVIOUS TASK		0